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**UTILITY
PATENT APPLICATION
TRANSMITTAL**

(Only for new nonprovisional applications under 37 CFR 1.63(b))

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Total Pages : 1

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APPLICATION ELEMENTS

See MPEP chapter 600 concerning utility patent application contents.

ADDRESS TO: Assistant Commissioner for Patents
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Washington, D.C. 20231JC8917 U.S. PTO
09/689761

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1. ☒ Fee Transmittal Form
(Submit an original, and a duplicate for fee processing)2. ☒ Specification [Total Pages 51]
(preferred arrangement set forth below)

- Descriptive title of the Invention
- Cross References to Related Applications
- Statement Regarding Fed sponsored R & D
- Reference to Microfiche Appendix
- Background of the Invention
- Brief Summary of the Invention
- Brief Description of the Drawings (if filed)
- Detailed Description
- Claim(s)
- Abstract of the Disclosure

3. ☒ Drawing(s) (35 USC 113) [Total sheets -10]4. ☒ Oath or Declaration [Total Pages - 3]a.1. ☐ Newly executed (original or copy)a.2. ☒ Unexecutedb. ☐ Copy from a prior application (37 CFR 1.63(d))
(for continuation/divisional with Box 17 completed)

[Note Box 5 below]

i. ☐ DELETION OF INVENTOR(S)Signed statement attached deleting inventor(s)
named in the prior application, see 37 CFR
1.63(d)(2) and 1.33(b).5. ☐ Incorporation By Reference
(usable if Box 4b is checked)The entire disclosure of the prior application, from which
a copy of the oath or declaration is supplied under Box
4b, is considered as being part of the disclosure of the
accompanying application and is hereby incorporated by
reference therein.

6. Microfiche Computer Program (Appendix)

7. ☐ Nucleotide and/or Amino Acid Sequence Submission
(if applicable, all necessary)

- a. ☐ Computer Readable Copy
- b. ☐ Paper Copy (identical to computer copy)
- c. ☐ Statement verifying identity of above copies

ACCOMPANYING APPLICATION PARTS

- 8. ☐ Assignment Papers (cover sheet & document(s))
- 9. ☐ 37 CFR 3.73(b) Statement ☐ Power of Attorney
(when there is an assignee)
- 10. ☐ English Translation Document (if applicable)
- 11. ☐ Information Disclosure Statement (IDS)/PTO-1449
☐ Copies of IDS Citations
- 12. ☐ Preliminary Amendment
- 13. ☒ Return Receipt Postcard (MPEP 503)
(Should be specifically itemized)
- 14. ☐ Small Entity Statement(s)
☐ Statement filed in prior application, Status still proper and desired
- 15. ☐ Certified Copy of Priority Document(s)
(if foreign priority is claimed)
- 16. ☐ Other

17. If a CONTINUING APPLICATION, check appropriate box and supply the requisite information:
☐ Continuation ☐ Divisional ☐ Continuation-in-part (CIP) of prior Application No.**18. CORRESPONDENCE ADDRESS**

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IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

In re application of :
Kazunaga SUZUKI :
Serial No. NEW : Attn: APPLICATION BRANCH
Filed October 13, 2000 : Attorney Docket No. 2000_1427A
LIQUID JETTING APPARATUS

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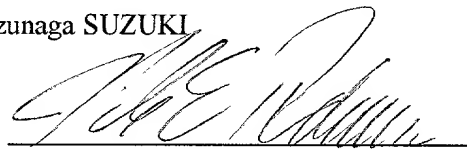
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Respectfully submitted,

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LIQUID JETTING APPARATUS

Field of the Invention

5 This invention relates to a liquid jetting apparatus having a head capable of jetting a drop of liquid from a nozzle. In particular, this invention is related to a liquid jetting apparatus that can prevent viscosity of liquid in a nozzle of a head from increasing.

10 BACKGROUND OF THE INVENTION

In a ink-jetting recording apparatus such as an ink-jetting printer or an ink-jetting plotter (a kind of liquid jetting apparatus), a recording head (head) can be moved in a main scanning direction, and a recording paper (a kind of recording medium) can be moved in a sub-scanning direction perpendicular to the main scanning direction. While the recording head is moved in the main scanning direction, a drop of ink can be jetted from a nozzle of the recording head onto the recording paper. Thus, an image including a character or the like can be recorded on the recording paper. For example, the drop of ink can be jetted by changing pressure of the ink in a pressure chamber communicating with the nozzle.

20 The pressure of the ink may be changed by utilizing a pressure-generating member, for example a piezoelectric vibrating member. In such a case, the piezoelectric vibrating member can be deformed based on a supplied driving-pulse in order to change a volume of the pressure chamber. When the volume of the pressure chamber is changed, the pressure of the ink in the pressure chamber may be changed. Then, the drop of ink is jetted from the nozzle.

30 The ink in the nozzles of the recording head is exposed to air. Thus, solvent of the ink such as water may gradually evaporate to increase a viscosity of the ink in the nozzle. In the case, quality of recorded images may deteriorate because the ink having a great viscosity may be jetted toward a direction deviated from a normal direction.

To prevent the viscosity of the ink in the nozzles from

increasing, some measures have been proposed. One of the measures is to forcibly cause ink having an increased viscosity to jet out from the nozzle outside an objective recording area (flushing operation). Another one of the measures is to cause a meniscus of the ink to minutely vibrate to stir the ink (stirring operation). The meniscus means a free surface of the ink exposed at an opening of the nozzle.

An execution amount of such a maintenance operation (flushing operation, stirring operation or the like) may be set suitably for a quality of images recorded in the objective recording area, in order to ensure the quality even at a position in the objective recording area furthest away from a waiting position of the recording head.

However, in the recording apparatus for printing onto a recording paper having a larger size such as a trimmed B-0 size (1030 mm × 1456 mm : JIS P 0138), a distance for which the recording head is moved in the main scanning direction is very long. Thus, when a flushing operation is conducted as a maintenance operation, volume of the ink jetted from the nozzle in the flushing operation is set large, in order to ensure that a first drop of ink can be normally jetted even when the first drop of ink is jetted at the position in the objective recording area furthest away from the waiting position of the recording head. Similarly, when a minutely-vibrating (stirring) operation is conducted as a maintenance operation, a number of operations (vibrations) of the pressure-generating member is set large.

Thus, if the flushing operation is conducted in the recording apparatus, as the volume of the ink jetted in the flushing operation is large, volume of the ink used for recording is relatively small. In addition, a waste-ink absorbing unit arranged for collecting the ink jetted in the flushing operation has to have a larger capacity.

In addition, if the minutely-vibrating operation is conducted in the recording apparatus, as the number of the operations (vibrations) of the pressure-generating member is large, a lifetime of the recording head is short.

SUMMARY OF THE INVENTION

The object of this invention is to solve the above problems, that is, to provide a liquid jetting apparatus such as an ink-jet recording apparatus that can more efficiently conduct a maintenance operation for preventing viscosity of ink in a nozzle from increasing in order to keep a condition for jetting a drop of the ink in good one.

In order to achieve the object, a liquid jetting apparatus includes: a head having a nozzle, adapted to receive jetting data corresponding to one scanning movement in a main scanning direction; a head-scanning mechanism for moving the head in the main scanning direction after the head has received the jetting data; a recovering unit for recovering a suitable viscosity of liquid in the nozzle from an increased viscosity thereof; a measuring timer for measuring at least a part of a time since a previous operation of the recovering unit has been completed; and a controller for controlling the recovering unit, based on the time measured by the measuring timer.

According to the feature, since the recovering unit is controlled based on at least a part of the time since the previous operation of the recovering unit has been completed, a maintenance operation for recovering the suitable viscosity of the liquid in the nozzle can be conducted more efficiently, dependently on a state of the liquid in the nozzle.

For example, the part of the time since the previous operation of the recovering unit has been completed may be a time since the previous operation of the recovering unit has been completed until the head completes receiving the jetting data. In the case, preferably, a next operation of the recovering unit is conducted just after the head has completed receiving the jetting data.

Alternatively, when the head-scanning mechanism is adapted to move the head from a waiting position in the main scanning direction after the head has received the jetting data and to move back the head to the waiting position again, the part of the time since the previous operation of the recovering unit has been completed may be a time since the head has been moved

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back to the waiting position again after being moved in the main scanning direction until the head completes receiving the jetting data. In this manner, it is taken in consideration that in the time since the previous operation of the recovering unit has been
5 completed, a receiving time of the jetting data may vary relatively widely dependently on the jetting data.

Preferably, the controller may be adapted to control the recovering unit, based on the jetting data itself.

In detail, when the head-scanning mechanism is adapted not
10 to move the head to an area over a position to which a last drop of the liquid is jetted in the one scanning movement in the main scanning direction (when a scanning area (scanning columns) may be changed), the controller is preferably adapted to control the recovering unit dependently on a distance for which the head is
15 moved in a next scanning movement in the main scanning direction, based on the jetting data corresponding to the next scanning movement. Alternatively, in the case, the controller is preferably adapted to control the recovering unit dependently on a distance for which the head has been moved in a previous
20 scanning movement in the main scanning direction.

Alternatively, the controller is preferably adapted to control the recovering unit, dependently on a distance for which the head is moved until a first drop of the liquid is jetted in a next scanning movement in the main scanning direction, based
25 on the jetting data corresponding to the next scanning movement.

Alternatively, when the head has a plurality of nozzles, and the recovering unit is adapted to recover a suitable viscosity of liquid in each of the plurality of nozzles from an increased viscosity thereof, respectively; the controller is preferably
30 adapted to control the recovering unit dependently on respective distances for which the head is moved until respective first drops of the liquid are jetted from the respective nozzles in a next scanning movement in the main scanning direction, based on the jetting data corresponding to the next scanning movement.

Alternatively, the controller is preferably adapted to
35 control the recovering unit, dependently on a proportion of the liquid jetted in a previous scanning movement in the main scanning

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direction.

Alternatively, when the head has a plurality of nozzles, and the recovering unit is adapted to recover a suitable viscosity of liquid in each of the plurality of nozzles from an increased viscosity thereof, respectively; the controller is preferably adapted to control the recovering unit, dependently on respective proportions of the liquid jetted from the respective nozzles in a previous scanning movement in the main scanning direction.

Alternatively, the controller is preferably adapted to control the recovering unit dependently on a proportion of the liquid jetted in a next scanning movement in the main scanning direction, based on the jetting data corresponding to the next scanning movement.

Alternatively, when the head has a plurality of nozzles, and the recovering unit is adapted to recover a suitable viscosity of liquid in each of the plurality of nozzles from an increased viscosity thereof, respectively; the controller is preferably adapted to control the recovering unit, dependently on respective proportions of the liquid jetted from the respective nozzles in a next scanning movement in the main scanning direction, based on the jetting data corresponding to the next scanning movement.

In addition, when the head has a plurality of nozzles in which a plurality of kinds of liquid are used, respectively, and the recovering unit is adapted to recover a suitable viscosity of liquid in each of the plurality of nozzles from an increased viscosity thereof, respectively; the controller is preferably adapted to control the recovering unit, based on characteristics of the respective kinds of liquid used in the respective nozzles.

In addition, when the liquid jetting apparatus further includes a sensor for detecting a state of environment where the liquid jetting apparatus is used, the controlling unit is preferably adapted to control the recovering unit, based on an output from the sensor.

In addition, when the liquid jetting apparatus further includes a capping unit capable of being moved between a position away from the head and a position for coming in contact with the head in order to seal the nozzle, the controlling unit is

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preferably adapted to bring the capping unit in contact with the head, based on the time measured by the measuring timer.

The recovering unit may be a minutely-vibrating unit for causing the liquid in the nozzle to minutely vibrate.

- 5 Alternatively, the recovering unit may be a flushing unit for causing the liquid in the nozzle to jet out from the nozzle outside an objective jetting area.

10 In addition, a controlling unit for controlling a liquid jetting apparatus including: a head having a nozzle, adapted to receive jetting data corresponding to one scanning movement in a main scanning direction; a head-scanning mechanism for moving the head in the main scanning direction after the head has received the jetting data; a recovering unit for recovering a suitable viscosity of liquid in the nozzle from an increased viscosity thereof; and a measuring timer for measuring at least a part of a time since a previous operation of the recovering unit has been completed; is characterized by that the controlling unit is adapted to control the recovering unit, based on the time measured by the measuring timer.

- 20 A computer system can materialize the whole controlling unit or only one or more components in the controlling unit.

This invention includes a storage unit capable of being read by a computer, storing a program for materializing the controlling unit in a computer system.

- 25 This invention also includes the program itself for materializing the controlling unit in the computer system.

This invention includes a storage unit capable of being read by a computer, storing a program including a command for controlling a second program executed by a computer system including a computer, the program is executed by the computer system to control the second program to materialize the controlling unit.

- 30 This invention also includes the program itself including the command for controlling the second program executed by the computer system including the computer, the program is executed by the computer system to control the second program to materialize the controlling unit.

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The storage unit may be not only a substantial object such as a floppy disk or the like, but also a network for transmitting various signals.

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BRIEF DESCRIPTION OF THE DRAWINGS

Fig.1 is a schematic perspective view of an ink-jetting recording apparatus of a first embodiment according to the invention;

10 Fig.2A is a schematic view for explaining a scanning range of a recording head when the ink-recording apparatus conducts a single-direction (one-way) printing;

Fig.2B is a schematic view for explaining a scanning range of a recording head when the ink-recording apparatus conducts a double-direction (forth and back) printing;

15 Fig.3A is a schematic view for explaining a movement of the recording head, the recording head being located at a waiting position;

20 Fig.3B is a schematic view for explaining the movement of the recording head, the recording head being moved from the waiting position to an objective recording area;

Fig.3C is a schematic view for explaining the movement of the recording head, the recording head being moved back from the objective recording area to the waiting position;

25 Fig.3D is a schematic view for explaining the movement of the recording head, the recording head being located at a home position;

Fig.4 is a sectional view of an example of a recording head;

Fig.5 is a schematic block diagram for explaining an electric structure of the recording head;

30 Fig.6 is a graph for explaining an example of a relationship between one-path times and execution amounts of maintenance operation;

35 Fig.7 is a graph for explaining an example of a relationship between waiting times and execution amounts of maintenance operation;

Fig.8 is a graph for explaining an example of a relationship between waiting times and execution amounts of maintenance

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Fig.9 is a graph for explaining an example of a relationship between waiting times and execution amounts of maintenance operation, when positions where first drops of ink are jetted in a current recording operation (scanning movement) are taken in consideration;

Fig.11 is a schematic block diagram for explaining an electric structure of the recording head, when the ink-jetting recording apparatus has a temperature sensor for detecting a temperature of environment where the ink-jetting recording apparatus is used and a humidity sensor for detecting a humidity thereof; and

BEST MODE FOR CARRYING OUT THE INVENTION

First embodiment

Fig.1 is a schematic perspective view of an ink-jetting printer 1 as a liquid jetting apparatus of a first embodiment according to the invention. The ink-jetting printer 1 includes a carriage 5, which has a cartridge holder 3 capable of holding an ink cartridge 2 and a recording head 4. The carriage 5 is adapted to be reciprocated in a main scanning direction by a head-scanning mechanism.

35 The head-scanning mechanism is formed by: a guide bar 6 horizontally extending in a housing, a pulse motor 7 arranged at a right portion of the housing, a driving pulley 8 connected

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The home position is a position that the recording head 4 is moved to and stays at when electric power supply is off or when a long time has passed since the last recording operation. When the recording head 4 stays at the home position, as shown in Fig.3D, a capping member 15 of the capping mechanism comes in contact with a nozzle plate 16 (see Fig.4) and seals nozzles 17 (see Fig.4). The capping member 15 is a tray-like member having a substantially square shape, being open upward, and made of an elastic material such as a rubber. A moisture retaining material such as felt is attached inside the capping member 15. When the recording head 4 is sealed by the capping member 15, an inside of the capping member 15 is kept in high humid condition. Thus, it can be prevented that solvent of the ink evaporates from the nozzles 17.

The waiting position is a starting position for moving the recording head 4 in the main scanning direction. That is, normally, the recording head 4 stays and waits at the waiting position. When a recording operation is started, the recording head 4 is moved from the waiting position to the objective recording area. Then, when the recording operation is completed, the recording head 4 is moved back to the waiting position.

In a case of the printer for the double-direction recording, with reference to Fig.2B, the recording head 4 is moved forth from the first waiting position WP1 to the second waiting position WP2 through the objective recording area, while jetting one or more drops of ink to the objective recording area. After that, the recording head 4 stays and waits at the second waiting position WP2. Then, the recording head 4 is moved back from the second waiting position WP2 to the first waiting position WP1 through the objective recording area, while jetting one or more drops of ink to the objective recording area. After that, the recording head 4 stays and waits at the first waiting position WP1. After that, the recording operation during moved forth and the recording operation during moved back are repeated in turn.

An ink-receiving member may be arranged under the waiting position for collecting ink discharged from the recording head 4 because of flushing operations (maintenance operations). In

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vibrating member when the piezoelectric vibrating member is charged, and can contract by deformation of the piezoelectric vibrating member when the piezoelectric vibrating member is discharged.

5 Preferably, the recording head 4 may be a many-color-recording head capable of recording with a different plurality of colors. Such a many-color-recording head has a plurality of head units. Respective predetermined colors are set for and used in the plurality of head units, respectively.

10 For example, as an example of a many-color-recording head
having four head units, a many-color-recording head may have:
a black head unit capable of jetting a drop of black ink, a cyan
head unit capable of jetting a drop of cyan ink, a magenta head
unit capable of jetting a drop of magenta ink, and a yellow head
15 unit capable of jetting a drop of yellow ink.
(Electric structure)

Then, an electric structure of the printer 1 is explained. As shown in Fig.5, the ink-jetting printer 1 has a printer controller 30 and a printing engine 31.

20 The printer controller 30 has: an outside interface
 (outside I/F) 32, a RAM 33 which is able to temporarily store
 various data, a ROM 34 which stores a controlling program or the
 like, a controlling part 11 including CPU or the like, an
 oscillating circuit 35 for generating a clock signal, an
25 operating-signal generating part 36 for generating an operating
 signal that is supplied into a recording head 4, an inside
 interface (inside I/F) 37 that is adapted to send the operating
 signal, dot-pattern-data (bit-map-data) developed according to
 printing data (jetting data) or the like to the print engine 31,
30 and a measuring timer 38.

The outside I/F 32 is adapted to receive printing data consisting of character codes, graphic functions, image data or the like from a host computer not shown or the like. In addition, a busy signal (BUSY) or an acknowledge signal (ACK) is adapted to be outputted to the host computer or the like through the outside I/F 32.

The RAM 33 has a receiving buffer, an intermediate buffer,

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In addition, the controlling part 11 controls a maintenance operation (a recovering operation) conducted before the recording operation by the recording head 4.

The measuring timer 38 is adapted to measure a time (an
5 one-path time) from a point of time when the previous maintenance
operation has been completed till a point of time when the
recording head has completed receiving the printing data for the
next recording operation through the recording operation for the
one lime (one path).

10 The print engine 31 includes a paper feeding motor 13 as
a paper feeding mechanism, a pulse motor 7 as a head scanning
mechanism, and an electric driving system 9 of the recording head
4.

Then, the electric driving system 39 of the recording head 4 is explained. As shown in Fig.5, the electric driving system 39 includes shift registers 40, latch circuits 41, level shifters 42 and switching units 43 and the piezoelectric vibrating members 21, which are electrically connected in the order. The shift registers 40 correspond to the respective nozzles 17 of the recording head 4, respectively. Similarly, the latch circuits 41 correspond to the respective nozzles 17, the level shifters 42 correspond to the respective nozzles 17, and the switching units 43 correspond to the respective nozzles 17, respectively. In addition, the piezoelectric vibrating members 21 correspond to the respective nozzles 17 of the recording head 4.

In the electric driving system 39, when a bit "1" of printing data is supplied to a switching unit 43, the switching unit 43 is closed (connected) and the operating signal (COM) is directly supplied to a corresponding piezoelectric vibrating member 21. Thus, the piezoelectric vibrating member 21 deforms according to a waveform of the operating signal. On the other hand, when a bit "0" of printing data is supplied to a switching unit 43, the switching unit 43 is opened (unconnected) and the operating signal (COM) is not supplied to a corresponding piezoelectric vibrating member 21.

As described above, based on the printing data, the operating signal may be selectively supplied to each

piezoelectric vibrating member 21. Thus, dependently on given printing data, a drop of the ink may be jetted from a nozzle 17 or a meniscus of ink may be caused to minutely vibrate.

(Operation of the printer)

- 5 Then, an operation of the printer 1 is explained with reference to Figs.2A to 3D.

When electric power is supplied to the printer 1, a necessary initializing operation is conducted at first. Then, the recording head 4 waits (stands by) at the waiting position
10 (as shown in Fig.3A). After printing data corresponding to one line is outputted from the outputting buffer of the RAM 33, the recording head 4 conducts a maintenance operation (recovering operation) before a recording operation for the one line.

The maintenance operation is conducted for keeping ability
15 of the recording head 4 to jet drops of the ink. The maintenance operation may be suitably selected from a flushing operation, a minutely-vibrating operation, and so on.

In detail, the flushing operation is an operation for forcibly causing ink to jet out from the recording head 4 toward
20 the ink-receiving member (capping member 15) outside the objective recording area. The flushing operation is conducted while the recording head 4 waits at the waiting position. Owing to the flushing operation, ink having an increased viscosity in and/or near to the nozzle 17 may be discharged out from the
25 recording head 4, and replaced with ink having a suitable viscosity.

As described above, the minutely-vibrating operation is an operation for causing a meniscus of ink to minutely vibrate, by causing a pressure chamber 22 to expand and/or contract in
30 such a manner that the ink may not be jetted. In the embodiment, the minutely-vibrating operation is conducted while the recording head 4 waits at the waiting position and while the recording head 4 is moved in the acceleration area.

An initial value of an execution amount of the maintenance
35 operation for a first scanning (recording) movement (first path) in the main scanning direction is set in such a manner that ability to jet drops of the ink may be satisfactory maintained even at

an end position X in the objective recording area furthest away from the waiting position (see Fig.2A), that is, in such a manner that a quality of a printed image may be ensured even at the end portion X.

5 For example, when a flushing operation is conducted as a maintenance operation, an initial value of a number of jetting a drop of the ink during the flushing operation (flushing-shot number) may be set at "200". Similarly, when a minutely-vibrating operation is conducted as a maintenance operation, an initial
10 value of a number of operations of the piezoelectric vibrating member 21 during the minutely-vibrating operation (number of times of minutely-vibrating) may be at "200".

If the flushing operation is conducted, the recording head 4 starts to be moved just after the flushing operation is completed.
15 If the minutely-vibrating operation is conducted, the recording head 4 starts to be moved at a suitable timing after completing receiving the printing data.

That is, after the maintenance operation is conducted, the recording operation is conducted in the objective recording area
20 based on the printing data.

After the recording operation in the first scanning movement (first path) has been completed (see Figs.3A and 3B), the recording head 4 is moved back to and waits at the waiting position (see Figs.3C and 3D). Then, the recording head 4 stays
25 and waits at the waiting position until the recording head 4 completes receiving printing data corresponding to a next line. After the recording head 4 has received the printing data corresponding to the next line transferred from the printer controller 30, a maintenance operation for a second scanning
30 movement (second path) is conducted.

An execution amount of the maintenance operation for the second scanning movement is set, based on a one-path time of the recording head 4 measured by the measuring timer 38.

That is, the controlling part 11 sets a flushing-shot
35 number for a flushing operation or a number of times of minutely-vibrating for a minutely-vibrating operation, based on the one-path time measured by the measuring timer 38. The one-path

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time means a time from a point of time when the maintenance operation for the first scanning movement has been completed till a point of time when the recording head has completed receiving the printing data for the second recording operation (second path), through the first recording operation (first path) and a return of the recording head 4 to the waiting position.

In detail, the controlling part 11 sets the flushing-shot number or the number of times of minutely-vibrating, based on maintenance setting data stored in the ROM 34. For example, the maintenance setting data may be given as table information as shown by a graph in Fig.6.

According to the maintenance setting data shown by the graph in Fig.6, an execution amount of the maintenance operation (the flushing-shot number or the number of times of minutely-vibrating) is "100", if the one-path time is 0 to 5 seconds. In addition, an execution amount of the maintenance operation is "200", if the one-path time is 25 seconds. In the case, the one-path time is 5 seconds if the recording head 4 starts to be moved again for a next recording operation just after or just when the recording head 4 has been moved back to the waiting position after a previous recording operation. That is, the one-path time may be changed mainly dependently on an amount of the printing data received by the recording head 4. Of course, when the recording head 4 is not moved in the whole scanning range based on the printing data, for example, when the recording head 4 is not moved over a position to which a last drop of the ink is jetted in the scanning movement, the one-path time may be also changed thereby.

When the one-path time is in a range of 5 to 25 seconds, the execution amount of the maintenance operation is proportional to the one-path time. That is, the execution amount of the maintenance operation is more when the one-path time is longer in the range.

Thus, the controlling part 11 sets the execution amount of the maintenance operation based on the one-path time, and causes a maintenance operation to be conducted based on the set execution amount.

For example, when the flushing operation is conducted for the printer 1 and the one-path time is 15 seconds, a number of "150" is set as the flushing-shot number. Then, a drop of the ink is jetted 150 times during the flushing operation.

5 Alternatively, when the one-path time is 5 seconds, that is, when the recording head 4 starts to be moved again for the second recording operation just after or just when the recording head 4 has been moved back to the waiting position after the first recording operation, a number of "100" is set as the flushing-shot
10 number. Then, a drop of the ink is jetted 100 times during the flushing operation. Thus, in the flushing operation, volume of the jetted ink may increase or decrease dependently on the one-path time of the recording head 4.

Similarly, when the minutely-vibrating operation is
15 conducted for the printer 1 and the one-path time is 15 seconds, a number of "150" is set as the number of times of minutely-vibrating. Alternatively, when the one-path time is 5 seconds, a number of "100" is set as the number of times of minutely-vibrating. Thus, in the minutely-vibrating operation, the number
20 of times of minutely-vibrating may increase or decrease dependently on the one-path time of the recording head 4.

As described above, if the execution amount of the maintenance operation is set dependently on the one-path time of the recording head 4, the maintenance operation is conducted
25 more efficiently while the quality of the printed image is ensured even at the end position in the objective recording area and while too much maintenance operation is avoided.

In detail, when the one-path time of the recording head 4 is relatively short, a time for which a meniscus of the ink
30 is exposed to air is also relatively short. In addition, it is possible that the meniscus remains vibrating because of the previous recording operation. That is, it may tend to be prevented that a viscosity of the ink in or near to the nozzle 17 increases. Thus, if the execution amount of the maintenance operation is
35 set relatively small, the quality of the printed image can be ensured even at the end position in the objective recording area.

On the other hand, when the one-path time of the recording

head 4 is relatively long, a time for which a meniscus of the ink is exposed to air is also relatively long. Then, the solvent of the ink tends to evaporate more. Thus, the viscosity of the ink in or near to the nozzle 17 may tend to rise to a degree affecting the quality of the printed image. Thus, the execution amount of the maintenance operation is set relatively large, in order to ensure the quality of the printed image even at the end position in the objective recording area.

In addition, when the one-path time of the recording head 4 is longer than a predetermined capping time (for example 25 seconds), that is, when the recording head 4 still has not completed receiving the printing data when the capping time has passed, the controlling part 11 outputs instructions for a capping operation. Based on the instructions for the capping operation, the recording head 4 is moved from the waiting position to the home position. Then, the capping member 15 is moved to come in contact with the nozzle plate 16, and seals the nozzles 17 (see Fig.3D). In such a capping state, the moisture retaining material, in which ink is contained, heightens humidity inside the capping member 15. Thus, it can be prevented that the solvent of the ink evaporates from the nozzles 17. Thus, it can be prevented that density of the ink in the recording head 4 increases too much.

For example, the capping state may be released when the recording head 4 has completed receiving the printing data (dot-pattern-data). When the capping state is released, the recording head 4 is moved back to the waiting position. The initial value of the execution amount of the maintenance operation for the first scanning movement may be used as the execution amount of the maintenance operation after the capping state.

In the embodiment, the third (third path) or more recording operation is conducted similarly to the second recording operation.

As described above, according to the first embodiment, when the flushing operation is conducted for the printer 1 as the maintenance operation, the volume of the ink jetted during the flushing operation can be reduced to only necessary volume depending on the one-path time of the recording head 4. Thus,

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of minutely-vibrating. Thus, in the minutely-vibrating operation, the number of times of minutely-vibrating may increase or decrease dependently on the carriage-waiting time of the recording head 4.

5 As described above, if the execution amount of the maintenance operation is set dependently on the carriage-waiting time of the recording head 4, the maintenance operation is conducted more efficiently while the quality of the printed image is ensured even at the end position in the objective recording
10 area and while too much maintenance operation is avoided.

In addition, when the carriage-waiting time of the recording head 4 is longer than a predetermined capping time (for example 20 seconds), that is, when the recording head 4 still has not completed receiving the printing data when the capping
15 time has passed, the controlling part 11 outputs instructions for a capping operation. Based on the instructions for the capping operation, the recording head 4 is moved from the waiting position to the home position. Then, the capping member 15 is moved to come in contact with the nozzle plate 16, and seals the nozzles
20 17 (see Fig.3D). In such a capping state, the moistening material, which ink is contained therein, heightens humidity inside the capping member 15. Thus, it can be prevented that the solvent of the ink evaporates from the nozzles 17. Thus, it can be prevented that density of the ink in the recording head 4 increases
25 too much.

Third embodiment

Then, a third embodiment of the invention is explained. Fig.8 is a graph for explaining a relationship between carriage-waiting times and execution amounts of maintenance
30 operation (flushing-shot numbers or numbers of times of minutely-vibrating) and a relationship between carriage-waiting times and capping times, in the third embodiment. The controlling part 11 of the third embodiment sets the execution amount of the maintenance operation by taking into account the printing columns
35 (the printing area) in the current recording operation, that is, by taking into account the scanning distance of the recording head 4 in the main scanning direction.

In detail, in the third embodiment, based on printing data for each line (each path), one of full-column setting data, half-column setting data and one-third-column setting data are respectively used. These three setting data are table data, respectively. The three setting data are stored in the ROM 34 as maintenance setting data, respectively.

The full-column setting data are adapted to be used when a scanning-end position of the scanning movement of the recording head 4 during the recording operation after the maintenance operation is located in a range between a substantially center position (half-column) of the objective recording area in the main scanning direction and the end position X (last-column) in the objective recording area furthest away from the waiting position.

The half-column setting data are adapted to be used when a scanning-end position of the scanning movement of the recording head 4 during the recording operation is located in a range between a substantially one-third position (one-third-column) of the objective recording area in the main scanning direction and the substantially center position (half-column) of the objective recording area in the main scanning direction.

The one-third-column setting data are adapted to be used when a scanning-end position of the scanning movement of the recording head 4 during the recording operation is located in a range to the substantially one-third position (one-third-column) of the objective recording area in the main scanning direction.

For example, the scanning-end position of the scanning movement of the recording head 4 can be obtained from the printing data developed in the RAM 33.

According to the respective setting data, the execution amount of the maintenance operation is proportional to the carriage-waiting time. That is, the execution amount of the maintenance operation is more when the carriage-waiting time is longer.

In addition, comparing the full-column setting data, the half-column setting data and the one-third-column setting data

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with each other, with respect to the same carriage-waiting time, the execution amount of the maintenance operation according to the full-column setting data is set most, the execution amount of the maintenance operation according to the half-column setting data is set less than that according to the full-column setting data, and the execution amount of the maintenance operation according to the one-third-column setting data is set less than that according to the half-column setting data.

The other structure is substantially the same as the second embodiment shown in Fig.7. In the third embodiment, the same numeral references correspond to the same elements as the second embodiment. The explanation of the same elements is not repeated.

The controlling part 11 of the third embodiment is adapted to set the execution amount of the maintenance operation, based on the above setting data, in such a manner that if a scanning distance of the current scanning movement of the recording head 4 is shorter, the execution amount of the maintenance operation is less.

If the scanning distance of the current scanning movement of the recording head 4 is shorter, that is, if the scanning area (columns) is smaller, no-jetting (free-running) distance of the recording head 4 is shorter even when a first drop of the ink is jetted at a position in the scanning area furthest away from the waiting position. Thus, the solvent of the ink may evaporate less. Thus, the viscosity of the ink in or near to the nozzle 17 may not tend to rise to a degree affecting the quality of the printed image. Thus, the quality of the printed image at the end position in the scanning area can be ensured, even if the execution amount of the maintenance operation is set relatively small.

On the other hand, if a scanning distance of the current scanning movement of the recording head 4 is longer, that is, if the scanning area (columns) is larger, no-jetting (free-running) distance of the recording head 4 may be longer when a first drop of the ink is jetted at a position in the scanning area furthest away from the waiting position. Then, the solvent of the ink tends to evaporate more. Thus, the viscosity of the ink in or near to the nozzle 17 may tend to rise to a degree

affecting the quality of the printed image. Thus, the execution amount of the maintenance operation is set relatively large, in order to ensure the quality of the printed image even at the end position in the scanning area.

5 With respect to the capping time, the capping time according to the full-column setting data is set shortest, the capping time according to the half-column setting data is set second shortest, and the capping time according to the one-third-column setting data is set longest.

10 That is, if a scanning distance of the current scanning movement of the recording head 4 is longer, no-jetting (free-running) distance of the recording head 4 may be longer when a first drop of the ink is jetted at a position in the scanning area furthest away from the waiting position. Then, the first
15 drop of the ink is liable to be jetted in a state wherein the viscosity of the ink has risen too much. Thus, the capping time is set relatively short, in order to ensure the quality of the printed image even at the end position in the scanning area.

20 On the other hand, if a scanning distance of the current scanning movement of the recording head 4 is shorter, no-jetting (free-running) distance of the recording head 4 is shorter even when a first drop of the ink is jetted at a position in the scanning area furthest away from the waiting position. Thus, the first
25 drop of the ink may hardly be jetted in a state wherein the viscosity of the ink has risen too much. Thus, the quality of the printed image at the end position in the scanning area can be ensured, even if the capping time is set relatively long.

30 In addition, in the third embodiment, the execution amount of the maintenance operation can be set by taking into account the scanning distance of the recording head 4 in the previous recording operation, instead of the scanning distance of the recording head 4 in the current recording operation.

35 That is, if the scanning distance of the previous scanning movement of the recording head 4 is shorter, no-jetting (free-running) distance and no-jetting (free-running) time of the recording head 4 from the scanning-end position to the waiting position are shorter, respectively. Thus, the solvent of the ink

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may evaporate less. Thus, the viscosity of the ink in or near to the nozzle 17 may not tend to rise to a degree affecting the quality of the printed image. Thus, the quality of the printed image in the next scanning area (including its end position) can be ensured, even if the execution amount of the maintenance operation is set smaller.

On the other hand, if a scanning distance of the previous scanning movement of the recording head 4 is longer, the above no-jetting (free-running) distance and the above no-jetting (free-running) time may be longer. Then, the solvent of the ink tends to evaporate more. Thus, the viscosity of the ink in or near to the nozzle 17 may tend to rise to a degree affecting the quality of the printed image. Thus, the execution amount of the maintenance operation is set larger, in order to ensure the quality of the printed image in the next scanning area (including its end position).

Similarly, the respective capping times can be set by taking into account the scanning distance of the recording head 4 in the previous recording operation.

That is, if a scanning distance of the previous scanning movement of the recording head 4 is long, as described above, the viscosity of the ink in or near to the nozzle 17 tends to rise too much. Thus, the capping time is set relatively short, in order to prevent the viscosity of the ink in or near to the nozzle 17 from rising too much.

On the other hand, if a scanning distance of the previous scanning movement of the recording head 4 is short, as described above, the viscosity of the ink in or near to the nozzle 17 hardly tends to rise too much. Thus, the quality of the printed image at the end position in the next scanning area can be ensured, even if the capping time is set relatively long.

In addition, it is also effective to set the execution amount of the maintenance operation by taking into account both of the scanning distance of the recording head 4 in the previous recording operation and the scanning distance of the recording head 4 in the current recording operation. For example, an average of the scanning distance in the previous recording operation and

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the scanning distance in the current recording operation can be used. Alternatively, longer one of the scanning distance in the previous recording operation and the scanning distance in the current recording operation can be used.

- 5 As described above, in the third embodiment, since the execution amount of the maintenance operation is set by taking into account the scanning distance of the recording head 4 in the recording operation, a degree of evaporation of the solvent of the ink, which may be caused by a no-jetting scanning of the recording head 4, can be considered. Thus, the maintenance operation may be conducted more suitably.

- 10 As a result, when the flushing operation is conducted, volume of the waste ink can be reduced more. When the minutely-vibrating operation is conducted, a lifetime of the piezoelectric vibrating member 21 can be extended more.

In addition, division of the respective setting data is not limited to the above embodiment, but could be set freely.

Fourth embodiment

- Then, a fourth embodiment of the invention is explained.
- 20 Fig.9 is a graph for explaining a relationship between carriage-waiting times and execution amounts of maintenance operation (flushing-shot numbers or numbers of times of minutely-vibrating) and a relationship between carriage-waiting times and capping times, in the fourth embodiment. The controlling part 11 of the fourth embodiment sets the execution amount of the maintenance operation by taking into account a scanning distance until a first drop of the ink is jetted in the recording operation.

- 25 In the case, the controlling part 11 can obtain the scanning distance of the recording head 4 until the first drop of the ink is jetted from the nozzle 17 in the current recording operation, through the printing data or the number of pulses supplied to the pulse motor 7. Then, the execution amount of the maintenance operation (a number of times of jetting a drop of the ink during the flushing operation or a number of times of actuating the piezoelectric vibrating member 21 during the minutely-vibrating operation) is set correspondingly to the carriage-waiting time

In the fourth embodiment, substantially similarly to the third embodiment, based on printing data for each line (each path), one of full-column setting data, half-column setting data and one-third-column setting data are respectively used. These three setting data are table data, respectively. The three setting data are stored in the ROM 34 as maintenance setting data, respectively.

The half-column setting data are adapted to be used when a first-jetting position of the recording head 4 during the current recording operation is located in a range between a substantially one-third position (one-third-column) of the objective recording area in the main scanning direction and the substantially center position (half-column) of the objective recording area in the main scanning direction.

For example, the first-jetting position of the recording head 4 can be obtained from the printing data developed in the RAM 33.

In addition, comparing the full-column setting data, the half-column setting data and the one-third-column setting data

with each other, with respect to the same carriage-waiting time, the execution amount of the maintenance operation according to the full-column setting data is set most, the execution amount of the maintenance operation according to the half-column setting data is set less than that according to the full-column setting data, and the execution amount of the maintenance operation according to the one-third-column setting data is set less than that according to the half-column setting data.

The other structure is substantially the same as the third embodiment shown in Fig.8. In the fourth embodiment, the same numeral references correspond to the same elements as the third embodiment. The explanation of the same elements is not repeated.

The controlling part 11 of the fourth embodiment is adapted to set the execution amount of the maintenance operation, based on the above setting data, in such a manner that if no-jetting (free-running) distance and no-jetting (free-running) time until the recording head 4 jets the first drop of the ink are shorter, the execution amount of the maintenance operation is less.

That is, if the no-jetting (free-running) distance and the no-jetting (free-running) time until the recording head 4 jets the first drop of the ink are shorter, the solvent of the ink may evaporate less. Thus, the viscosity of the ink in or near to the nozzle 17 may not tend to rise to a degree affecting the quality of the printed image. Thus, the quality of the image printed by the first-jetted drop of the ink can be ensured, even if the execution amount of the maintenance operation is set smaller.

On the other hand, if the no-jetting (free-running) distance and the no-jetting (free-running) time until the recording head 4 jets the first drop of the ink are longer, the solvent of the ink tends to evaporate more. Thus, the viscosity of the ink in or near to the nozzle 17 may tend to rise to a degree affecting the quality of the printed image. Thus, the execution amount of the maintenance operation is set larger, in order to ensure the quality of the image printed by the first-jetted drop of the ink.

With respect to the capping time, the capping time

according to the full-column setting data is set shortest, the capping time according to the half-column setting data is set second shortest, and the capping time according to the one-third-column setting data is set longest.

5 That is, if the no-jetting (free-running) distance and the no-jetting (free-running) time of the recording head 4 are longer, the capping time is set relatively short, because the first drop of the ink is liable to be jetted in a state wherein the viscosity of the ink has risen too much.

10 On the other hand, if the no-jetting (free-running) distance and the no-jetting (free-running) time of the recording head 4 are shorter, the capping time is set relatively long, because the first drop of the ink may be hardly jetted in a state wherein the viscosity of the ink has risen too much.

15 As described above, in the fourth embodiment, since the execution amount of the maintenance operation is set by taking into account the first-jetting position where the recording head 4 jets the first drop of the ink in the recording operation, a degree of evaporation of the solvent of the ink, which may be
20 caused by a no-jetting scanning of the recording head 4, can be considered more accurately. Thus, the maintenance operation may be conducted more suitably.

 As a result, when the flushing operation is conducted, volume of the waste ink can be reduced more. When the
25 minutely-vibrating operation is conducted, a lifetime of the piezoelectric vibrating member 21 can be extended more.

 In addition, division of the respective setting data is not limited to the above embodiment, but could be set freely.

 In addition, the "first drop of the ink" may mean not only
30 the first drop of the ink for the whole recording head 4 i.e. for all the nozzles 17, but also the first drop of the ink for each of the nozzles 17. In the latter case, the execution amount of the maintenance operation may be set for each of the nozzles 17. In the case, the maintenance operation may be conducted
35 further more suitably.

Fifth embodiment

 Then, a fifth embodiment of the invention is explained.

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Fig.10 is a graph for explaining a relationship between carriage-waiting times and execution amounts of maintenance operation (flushing-shot numbers or numbers of times of minutely-vibrating) and a relationship between carriage-waiting times and capping times, in the fifth embodiment. The controlling part 11 of the fifth embodiment sets the execution amount of the maintenance operation by taking into account ink-jetting ratio (print duty) in the recording operation. The print duty means a ratio of recording dots, that is, a ratio of the number of dots that are actually recorded to the total number of dots that can be recorded in one scanning movement.

In detail, in the fifth embodiment, based on printing data for each line (each path), one of 20% setting data, 20%-50% setting data and 50% setting data are respectively used. These three setting data are table data, respectively. The three setting data are stored in the ROM 34 as maintenance setting data, respectively.

The 20% setting data are adapted to be used when a print duty of the previous recording operation is not more than 20%.

The 20%-50% setting data are adapted to be used when a print duty of the previous recording operation is more than 20% and less than 50%.

The 50% setting data are adapted to be used when a print duty of the previous recording operation is not less than 50%.

For example, when the number of the nozzles 17 is 64 and the number of dots in the main scanning direction is 1000, the total number of dots is 64000 (64×1000). In the case, when the number of dots that have been actually recorded is 12800, the print duty is 20%. Similarly, when the number of dots that have been actually recorded is 32000, the print duty is 50%.

For example, the number of dots that have been actually recorded can be obtained from the printing data (dot-pattern-data) developed in the RAM 33.

According to the respective setting data, the execution amount of the maintenance operation is proportional to the carriage-waiting time. That is, the execution amount of the maintenance operation is more when the carriage-waiting time is

longer.

In addition, comparing the 20% setting data, the 20%-50% setting data and the 50% setting data with each other, with respect to the same carriage-waiting time, the execution amount of the maintenance operation according to the 20% setting data is set most, the execution amount of the maintenance operation according to the 20%-50% setting data is set less than that according to the 20% setting data, and the execution amount of the maintenance operation according to the 50% setting data is set less than that according to the 20%-50% setting data.

The other structure is substantially the same as the second embodiment shown in Fig.7. In the fifth embodiment, the same numeral references correspond to the same elements as the second embodiment. The explanation of the same elements is not repeated.

The controlling part 11 of the fifth embodiment is adapted to set the execution amount of the maintenance operation, based on the above setting data, in such a manner that if a ratio of recording dots (print duty) of the previous recording operation is higher, the execution amount of the maintenance operation is less.

A higher print duty of the previous recording operation means that a frequency of jetting a drop of the ink from the respective nozzles 17 was higher on the average. That is, in the case, the viscosity of the ink in or near to the nozzle 17 may not tend to rise to a degree affecting the quality of the printed image. Thus, the quality of the printed image in the current recording area can be ensured, even if the execution amount of the maintenance operation is set smaller.

On the other hand, a lower print duty of the previous recording operation means that a frequency of jetting a drop of the ink from the respective nozzles 17 was lower on the average. That is, in the case, the viscosity of the ink in or near to the nozzle 17 may tend to rise to a degree affecting the quality of the printed image. Thus, the execution amount of the maintenance operation is set relatively large, in order to ensure the quality of the printed image in the current recording area.

With respect to the capping time, the capping time

according to the 20% setting data is set shortest, the capping time according to the 20%-50% setting data is set second shortest, and the capping time according to the 50% setting data is set longest.

5 That is, if a print duty of the previous recording operation is lower, the viscosity of the ink in or near to the nozzle 17 may rise to a degree affecting the quality of the printed image in a relatively shorter time. Thus, the capping time is set relatively short, in order to ensure the quality of the printed
10 image even at an end position in the current recording area.

On the other hand, if a print duty of the previous recording operation is higher, the viscosity of the ink in or near to the nozzle 17 may rise to a degree affecting the quality of the printed image in a relatively longer time. Thus, the quality of the printed
15 image at the end position in the current recording area can be ensured, even if the capping time is set relatively long.

In addition, in the fifth embodiment, the execution amount of the maintenance operation can be set by taking into account the print duty of the recording head 4 in the current recording
20 operation, instead of the print duty of the recording head 4 in the previous recording operation.

That is, a higher print duty of the current recording operation means that a frequency of jetting a drop of the ink from the respective nozzles 17 is higher on the average. That
25 is, in the case, the viscosity of the ink in or near to the nozzle 17 may not tend to rise to a degree affecting the quality of the printed image. Thus, the quality of the printed image in the current recording area can be ensured, even if the execution amount of the maintenance operation is set smaller.

30 On the other hand, a lower print duty of the current recording operation means that a frequency of jetting a drop of the ink from the respective nozzles 17 is lower on the average. That is, in the case, the viscosity of the ink in or near to the nozzle 17 may tend to rise to a degree affecting the quality of
35 the printed image. Thus, the execution amount of the maintenance operation is set relatively large, in order to ensure the quality of the printed image in the current recording area.

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Similarly, the respective capping times can be set by taking into account the print duty in the current recording operation.

That is, if a print duty of the current recording operation
5 is lower, no-jetting (free-running) distance and no-jetting (free-running) time until a first drop of the ink is jetted in the current recording operation may be longer. Thus, the capping time is set relatively short, in order to ensure the quality of the image printed by the first drop of the ink.

10 On the other hand, if a print duty of the current recording operation is higher, no-jetting (free-running) distance and no-jetting (free-running) time until a first drop of the ink is jetted in the current recording operation may be shorter. Thus, the quality of the image printed by the first drop of the ink
15 can be ensured, even if the capping time is set relatively long.

In addition, it is also effective to set the execution amount of the maintenance operation by taking into account both of the print duty in the previous recording operation and the print duty in the current recording operation. For example, an
20 average of the print duty in the previous recording operation and the print duty in the current recording operation can be used. Alternatively, smaller one of the print duty in the previous recording operation and the print duty in the current recording operation can be used.

25 As described above, in the fifth embodiment, since the execution amount of the maintenance operation is set by taking into account the print duty in the recording operation, a frequency of jetting a drop of the ink in the recording operation can be considered. Thus, the maintenance operation may be
30 conducted more suitably.

As a result, when the flushing operation is conducted, volume of the waste ink can be reduced more. When the minutely-vibrating operation is conducted, a lifetime of the piezoelectric vibrating member 21 can be extended more.

35 In addition, division of the respective setting data is not limited to the above embodiment, but could be set freely.

In addition, the "print duty" may mean not only the print

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duty for the whole recording head 4 i.e. for all the nozzles 17, but also the print duty for each of the nozzles 17. In the latter case, the execution amount of the maintenance operation may be set for each of the nozzles 17. In the case, the maintenance
5 operation may be conducted further more suitably.

In the above embodiments, the controlling part 11 can set the execution amount of the maintenance operation, by taking into account a kind (characteristic) of ink used for the recording
10 operation. Thus, it can be considered that degree of increase in the viscosity of the ink, which may be caused by evaporation of the solvent of the ink, depends on the kind of the ink.

For example, with respect to ink of a dark color such as black, the viscosity of the ink may tend to rise by evaporation
15 of the solvent of the ink. On the other hand, with respect to ink of a light color such as yellow, light magenta or light cyan, the viscosity of the ink may not tend to rise by evaporation of the solvent of the ink so much. In addition, with respect to ink made of a pigment, the viscosity of the ink may tend to rise by
20 evaporation of the solvent of the ink. On the other hand, with respect to ink made of a dye, the viscosity of the ink may not tend to rise by evaporation of the solvent of the ink so much.

Thus, the execution amount of the maintenance operation for the ink of the dark color may be set larger than that for
25 the ink of the light color. Similarly, the execution amount of the maintenance operation for the ink made of the pigment may be set larger than that for the ink made of the dye. Thus, even if the degree of increase in the viscosity of the ink depends on the kind of the ink, the maintenance operation may be conducted
30 suitably for the ink.

In detail, when a head unit uses ink of a light color such as yellow, light magenta or light cyan, a coefficient is set as "1". Then, the maintenance operation may be conducted according to just the execution amount of the maintenance operation, which
35 has been set based on the carriage-waiting time of the recording head 4 or the like.

In addition, when a head unit uses ink of a little light

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is higher and the viscosity of the ink itself may tend to rise if the temperature is lower. Thus, in these cases, the coefficient is set as "2". Then, the maintenance operation may be conducted according to twice the execution amount of the maintenance operation set based on the carriage-waiting time of the recording head 4 or the like.

As described above, if the execution amount of the maintenance operation is set by taking into account a state of environment where the ink-jetting printer 1 is used, degree of evaporation of the solvent of the ink can be considered more and the maintenance operation may be conducted more suitably.

Although the ink-jetting printer 1 shown in Fig.11 is provided with both of the temperature sensor 51 and the humidity sensor 52, it is possible to provide only one of the temperature sensor 51 and the humidity sensor 52. In addition, any other sensor for detecting the state of the environment may be provided, instead of or in addition to the temperature sensor 51 and the humidity sensor 52.

In addition, the above embodiments can be variously modified in a scope of claimed invention.

For example, a pressure-generating member for changing the volume of the pressure chamber 22 is not limited to the piezoelectric vibrating member 21. For example, a pressure-generating member can consist of a magnetostrictive device. In the case, the magnetostrictive device causes the pressure chamber 22 to expand and contract, thus, changes the pressure of the ink in the pressure chamber 22. Alternatively, a pressure-generating member can consist of a heating device. In the case, the heating device causes an air bubble in the pressure chamber 22 to expand and contract, thus, changes the pressure of the ink in the pressure chamber 22.

In addition, as described above, the printer controller 30 can be materialized by a computer system. A program for materializing the above one or more components in a computer system, and a storage unit 201 storing the program and capable of being read by a computer, are intended to be protected by this

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application.

In addition, when the above one or more components may be materialized in a computer system by using a general program such as an OS, a program including a command or commands for controlling the general program, and a storage unit 202 storing the program and capable of being read by a computer, are intended to be protected by this application.

Each of the storage units 201 and 202 can be not only a substantial object such as a floppy disk or the like, but also a network for transmitting various signals.

The above description is given for the ink-jetting printer 1 as a liquid jetting apparatus of a first embodiment according to the invention. However, this invention is intended to apply to general liquid jetting apparatuses widely. A liquid may be glue, nail polish or the like, instead of the ink.

As described above, according to the invention, since the recovering unit is controlled based on at least a part of the time since the previous operation of the recovering unit has been completed, a maintenance operation for recovering the suitable viscosity of the liquid in the nozzle can be conducted more efficiently, dependently on a state of the liquid in the nozzle.

For example, when the flushing operation of jetting out the liquid from the head outside the objective recording area is conducted, volume of the liquid jetted during the flushing operation can be reduced to only necessary volume. Thus, volume of the liquid used for the recording operations can be relatively increased. That is, the liquid can be used more efficiently. In addition, a collecting unit for collecting the liquid jetted during the flushing operation can have only a smaller capacity.

Alternatively, when the minutely-vibrating operation of changing the pressure of the liquid in the pressure chamber not to jet out the liquid and to cause a meniscus of the liquid to minutely vibrate is conducted, the number of times the pressure-generating member is actuated during the minutely-vibrating operation can be reduced to only a necessary number of times. Thus, a lifetime of the pressure-generating member can

be extended.

Figure 1 consists of 12 bar charts, labeled (a) through (l), each representing a different fish species. The x-axis for all charts is 'Month' with categories: Jan, Feb, Mar, Apr, May, Jun, Jul, Aug, Sep, Oct, Nov, Dec. The y-axis is 'Percentage of total catch' ranging from 0 to 100. The species and their approximate catch percentages by month are as follows:

- (a) Atlantic herring: Jan (10%), Feb (10%), Mar (10%), Apr (10%), May (10%), Jun (10%), Jul (10%), Aug (10%), Sep (10%), Oct (10%), Nov (10%), Dec (10%).
- (b) Atlantic mackerel: Jan (10%), Feb (10%), Mar (10%), Apr (10%), May (10%), Jun (10%), Jul (10%), Aug (10%), Sep (10%), Oct (10%), Nov (10%), Dec (10%).
- (c) Atlantic cod: Jan (10%), Feb (10%), Mar (10%), Apr (10%), May (10%), Jun (10%), Jul (10%), Aug (10%), Sep (10%), Oct (10%), Nov (10%), Dec (10%).
- (d) Atlantic plaice: Jan (10%), Feb (10%), Mar (10%), Apr (10%), May (10%), Jun (10%), Jul (10%), Aug (10%), Sep (10%), Oct (10%), Nov (10%), Dec (10%).
- (e) Atlantic sole: Jan (10%), Feb (10%), Mar (10%), Apr (10%), May (10%), Jun (10%), Jul (10%), Aug (10%), Sep (10%), Oct (10%), Nov (10%), Dec (10%).
- (f) Atlantic haddock: Jan (10%), Feb (10%), Mar (10%), Apr (10%), May (10%), Jun (10%), Jul (10%), Aug (10%), Sep (10%), Oct (10%), Nov (10%), Dec (10%).
- (g) Atlantic whiting: Jan (10%), Feb (10%), Mar (10%), Apr (10%), May (10%), Jun (10%), Jul (10%), Aug (10%), Sep (10%), Oct (10%), Nov (10%), Dec (10%).
- (h) Atlantic salmon: Jan (10%), Feb (10%), Mar (10%), Apr (10%), May (10%), Jun (10%), Jul (10%), Aug (10%), Sep (10%), Oct (10%), Nov (10%), Dec (10%).
- (i) Atlantic trout: Jan (10%), Feb (10%), Mar (10%), Apr (10%), May (10%), Jun (10%), Jul (10%), Aug (10%), Sep (10%), Oct (10%), Nov (10%), Dec (10%).
- (j) Atlantic sea bass: Jan (10%), Feb (10%), Mar (10%), Apr (10%), May (10%), Jun (10%), Jul (10%), Aug (10%), Sep (10%), Oct (10%), Nov (10%), Dec (10%).
- (k) Atlantic turbot: Jan (10%), Feb (10%), Mar (10%), Apr (10%), May (10%), Jun (10%), Jul (10%), Aug (10%), Sep (10%), Oct (10%), Nov (10%), Dec (10%).
- (l) Atlantic halibut: Jan (10%), Feb (10%), Mar (10%), Apr (10%), May (10%), Jun (10%), Jul (10%), Aug (10%), Sep (10%), Oct (10%), Nov (10%), Dec (10%).

the controller is adapted to control the recovering unit, dependently on a distance for which the head is moved in a next scanning movement in the main scanning direction, based on the jetting data corresponding to the next scanning movement.

- the controller is adapted to control the recovering unit, dependently on a distance for which the head has been moved in a previous scanning movement in the main scanning direction.

8. A liquid jetting apparatus according to claim 4, wherein:
the head has a plurality of nozzles,
the recovering unit is adapted to recover a suitable
viscosity of liquid in each of the plurality of nozzles from an
increased viscosity thereof, respectively, and

9. A liquid jetting apparatus according to claim 4, wherein:
the controller is adapted to control the recovering unit,

dependently on a proportion of the liquid jetted in a previous scanning movement in the main scanning direction.

10. A liquid jetting apparatus according to claim 4, wherein:
the head has a plurality of nozzles,
the recovering unit is adapted to recover a suitable viscosity of liquid in each of the plurality of nozzles from an increased viscosity thereof, respectively, and

the controller is adapted to control the recovering unit, dependently on respective proportions of the liquid jetted from the respective nozzles in a previous scanning movement in the main scanning direction.

11. A liquid jetting apparatus according to claim 4, wherein:
the controller is adapted to control the recovering unit, dependently on a proportion of the liquid jetted in a next scanning movement in the main scanning direction, based on the jetting data corresponding to the next scanning movement.

12. A liquid jetting apparatus according to claim 4, wherein:
the head has a plurality of nozzles,
the recovering unit is adapted to recover a suitable viscosity of liquid in each of the plurality of nozzles from an increased viscosity thereof, respectively, and

the controller is adapted to control the recovering unit, dependently on respective proportions of the liquid jetted from the respective nozzles in a next scanning movement in the main scanning direction, based on the jetting data corresponding to the next scanning movement.

13. A liquid jetting apparatus according to claim 1, wherein:
the head has a plurality of nozzles in which a plurality of kinds of liquid are used, respectively,

the recovering unit is adapted to recover a suitable viscosity of liquid in each of the plurality of nozzles from an increased viscosity thereof, respectively, and

the controller is adapted to control the recovering unit,

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based on characteristics of the respective kinds of liquid used in the respective nozzles.

14. A liquid jetting apparatus according to claim 1, further comprising:

a sensor for detecting a state of environment where the liquid jetting apparatus is used,
wherein

the controller is adapted to control the recovering unit, based on an output from the sensor.

15. A liquid jetting apparatus according to claim 1, further comprising:

a capping unit capable of being moved between a position away from the head and a position for coming in contact with the head in order to seal the nozzle,
wherein

the controller is adapted to bring the capping unit in contact with the head, based on the time measured by the measuring timer.

16. A liquid jetting apparatus according to claim 1, wherein:

the recovering unit is a minutely-vibrating unit for causing the liquid in the nozzle to minutely vibrate.

17. A liquid jetting apparatus according to claim 16, wherein:

the recovering unit is a flushing unit for causing the liquid in the nozzle to jet out from the nozzle outside an objective jetting area.

18. A controlling unit for controlling a liquid jetting apparatus including: a head having a nozzle, adapted to receive jetting data corresponding to one scanning movement in a main scanning direction; a head-scanning mechanism for moving the head in the main scanning direction after the head has received the jetting data; a recovering unit for recovering a suitable viscosity of liquid in the nozzle from an increased viscosity

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thereof; and a measuring timer for measuring at least a part of a time since a previous operation of the recovering unit has been completed;

wherein

the controlling unit is adapted to control the recovering unit, based on the time measured by the measuring timer.

19. A controlling unit according to claim 18, wherein:

the measuring timer is adapted to measure a time since the previous operation of the recovering unit has been completed until the head completes receiving the jetting data.

20. A controlling unit according to claim 18, wherein:

the head-scanning mechanism is adapted to move the head from a waiting position in the main scanning direction after the head has received the jetting data, and to move back the head to the waiting position again, and

the measuring timer is adapted to measure a time since the head has been moved back to the waiting position again after being moved in the main scanning direction until the head completes receiving the jetting data.

21. A controlling unit according to claim 18, wherein:

the controlling unit is adapted to control the recovering unit, based on the jetting data.

22. A controlling unit according to claim 21, wherein:

the head-scanning mechanism is adapted not to move the head to an area over a position to which a last drop of the liquid is jetted in the one scanning movement in the main scanning direction, and

the controlling unit is adapted to control the recovering unit, dependently on a distance for which the head is moved in a next scanning movement in the main scanning direction, based on the jetting data corresponding to the next scanning movement.

23. A controlling unit according to claim 21, wherein:

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the head-scanning mechanism is adapted not to move the head to an area over a position to which a last drop of the liquid is jetted in the one scanning movement in the main scanning direction, and

the controlling unit is adapted to control the recovering unit, dependently on a distance for which the head has been moved in a previous scanning movement in the main scanning direction.

24. A controlling unit according to claim 21, wherein:

the controlling unit is adapted to control the recovering unit, dependently on a distance for which the head is moved until a first drop of the liquid is jetted in a next scanning movement in the main scanning direction, based on the jetting data corresponding to the next scanning movement.

25. A controlling unit according to claim 21, wherein:

the head has a plurality of nozzles,

the recovering unit is adapted to recover a suitable viscosity of liquid in each of the plurality of nozzles from an increased viscosity thereof, respectively, and

the controlling unit is adapted to control the recovering unit, dependently on respective distances for which the head is moved until respective first drops of the liquid are jetted from the respective nozzles in a next scanning movement in the main scanning direction, based on the jetting data corresponding to the next scanning movement.

26. A controlling unit according to claim 21, wherein:

the controlling unit is adapted to control the recovering unit, dependently on a proportion of the liquid jetted in a previous scanning movement in the main scanning direction.

27. A controlling unit according to claim 21, wherein:

the head has a plurality of nozzles,

the recovering unit is adapted to recover a suitable viscosity of liquid in each of the plurality of nozzles from an increased viscosity thereof, respectively, and

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unit, based on an output from the sensor.

32. A controlling unit according to claim 18, wherein:

the liquid jetting apparatus further includes a capping unit capable of being moved between a position away from the head and a position for coming in contact with the head in order to seal the nozzle, and

the controlling unit is adapted to bring the capping unit in contact with the head, based on the time measured by the measuring timer.

33. A storage unit capable of being read by a computer, storing a program for materializing a controlling unit for controlling a liquid jetting apparatus including; a head having a nozzle, adapted to receive jetting data corresponding to one scanning movement in a main scanning direction; a head-scanning mechanism for moving the head in the main scanning direction after the head has received the jetting data; a recovering unit for recovering a suitable viscosity of liquid in the nozzle from an increased viscosity thereof; and a measuring timer for measuring at least a part of a time since a previous operation of the recovering unit has been completed;

wherein the controlling unit is adapted to control the recovering unit, based on the time measured by the measuring timer.

34. A storage unit capable of being read by a computer, storing a program including a command for controlling a second program executed by a computer system including a computer, the program is executed by the computer system to control the second program to materialize a controlling unit for controlling a liquid jetting apparatus including; a head having a nozzle, adapted to receive jetting data corresponding to one scanning movement in a main scanning direction; a head-scanning mechanism for moving the head in the main scanning direction after the head has received the jetting data; a recovering unit for recovering a suitable viscosity of liquid in the nozzle from an increased viscosity thereof; and a measuring timer for measuring at least a part of

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a time since a previous operation of the recovering unit has been completed;

wherein the controlling unit is adapted to control the recovering unit, based on the time measured by the measuring timer.

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ABSTRACT

A liquid jetting apparatus of the invention includes a head having a nozzle. The head is adapted to receive jetting data corresponding to one scanning movement in a main scanning direction. The head is moved in the main scanning direction, after the head has received the jetting data. A suitable viscosity of liquid in the nozzle is recovered from an increased viscosity thereof by operating a recovering unit. A measuring timer is adapted to measure at least a part of a time since a previous operation of the recovering unit has been completed. A controller is adapted to control the recovering unit, based on the time measured by the measuring timer.

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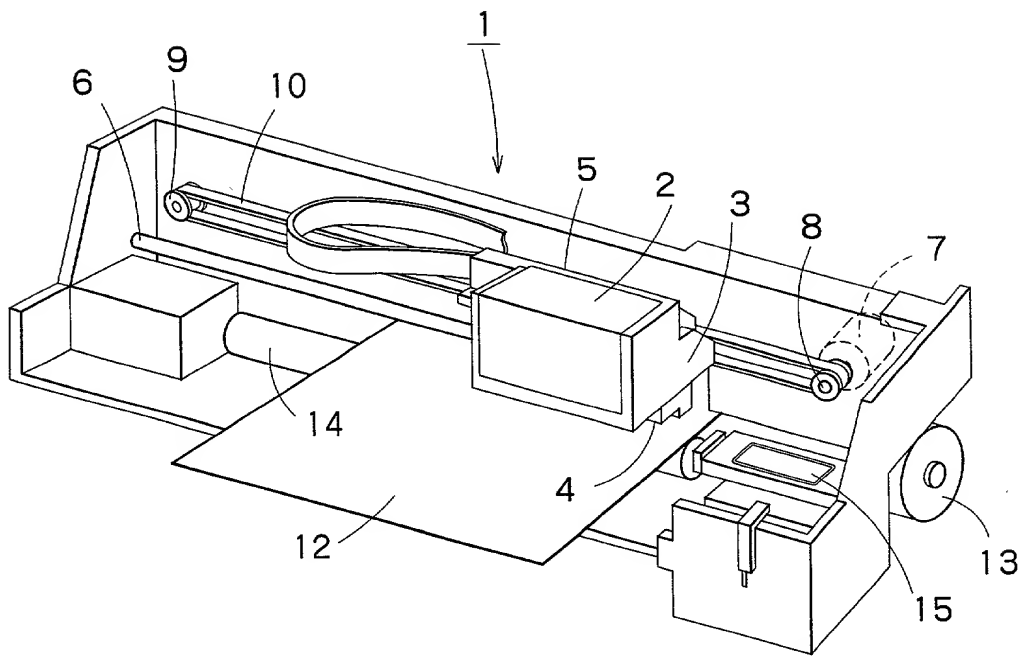


FIG. 1

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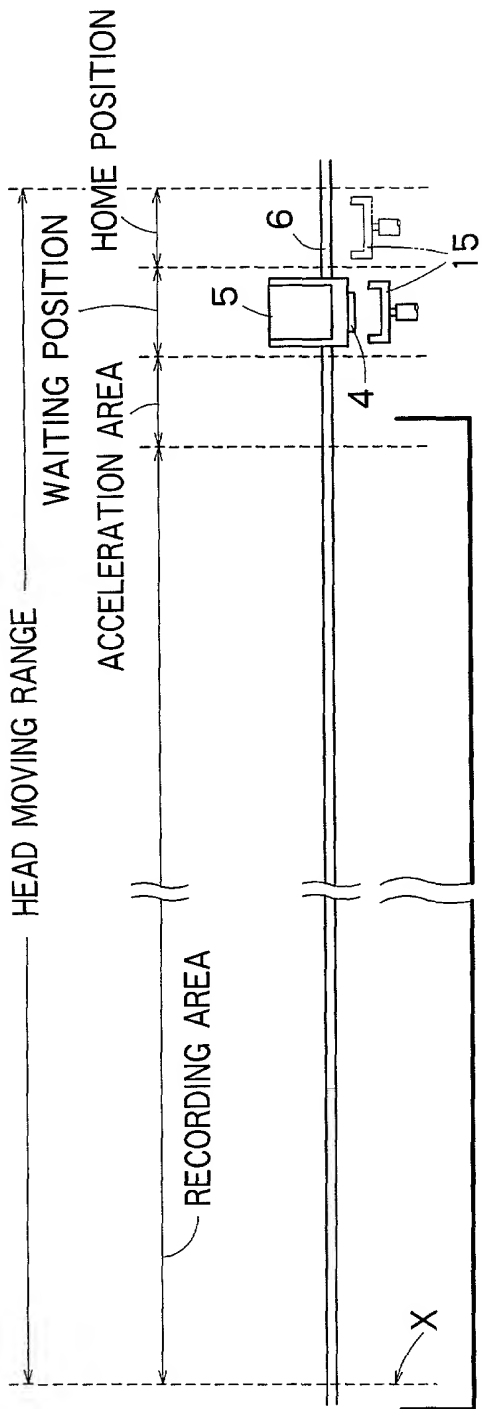


FIG. 2A

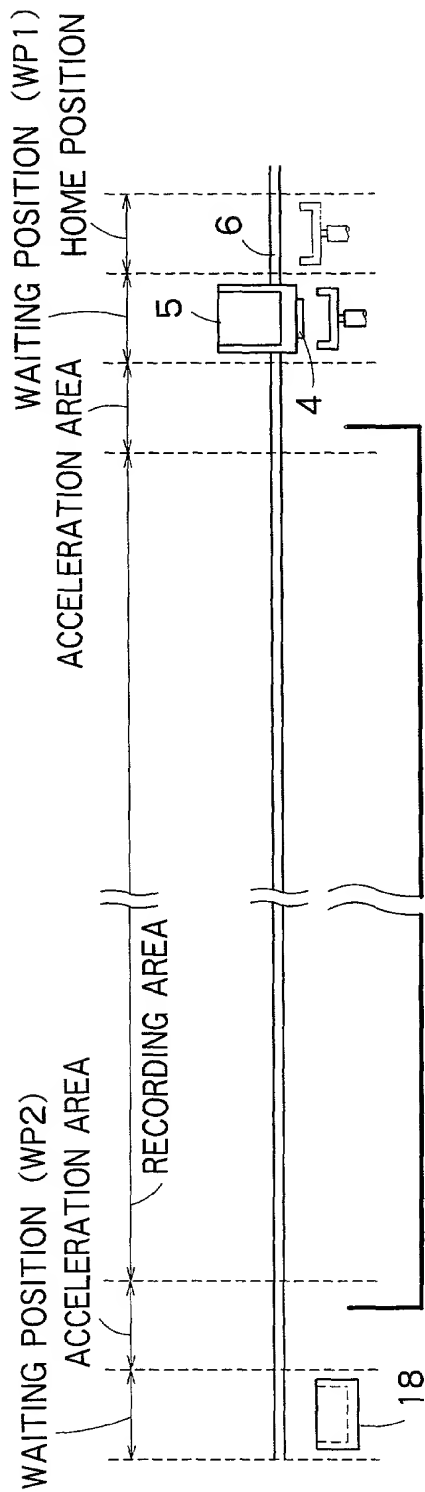
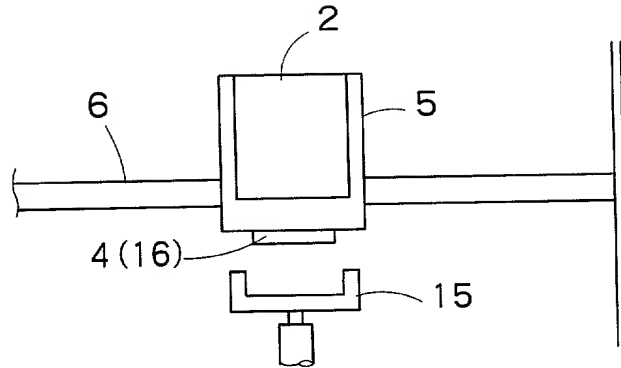


FIG. 2B

FIG. 3A



F I G. 3B

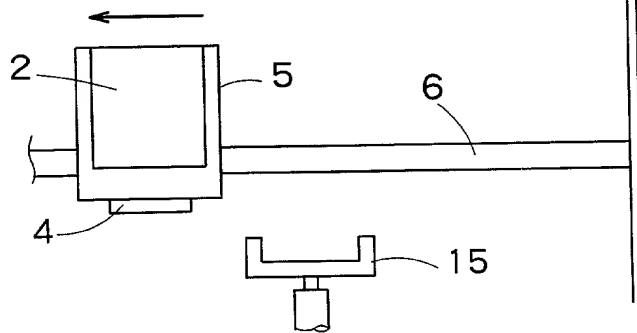


FIG. 3C

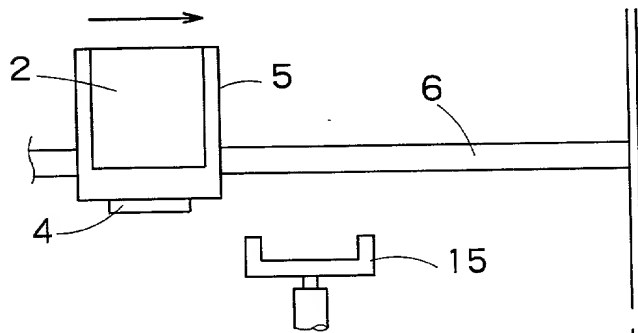
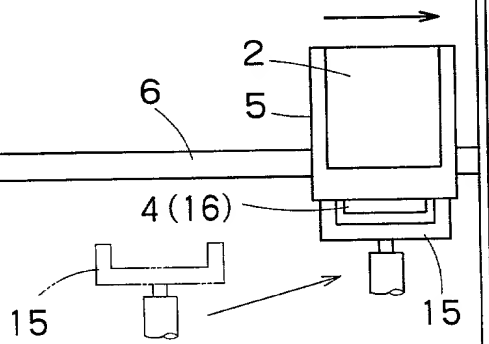


FIG. 3D



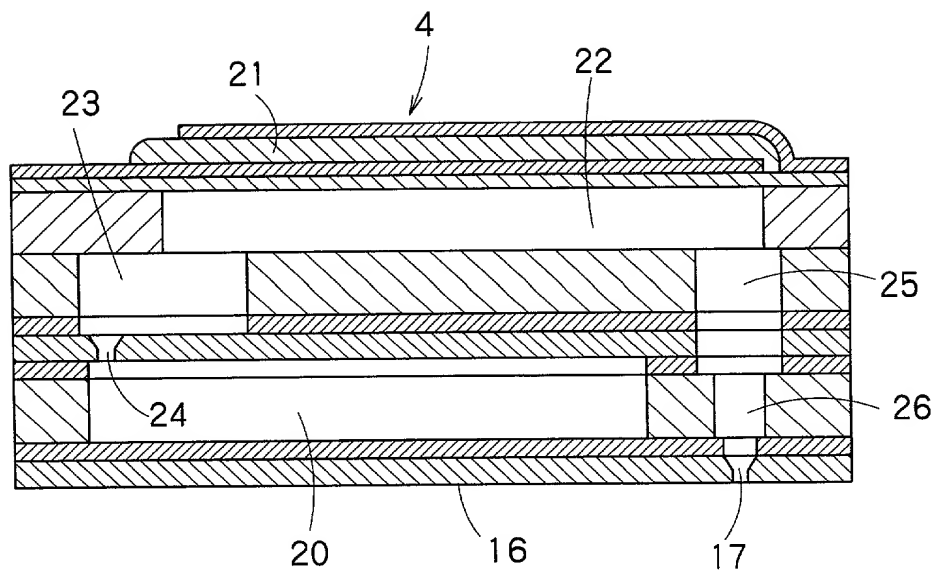
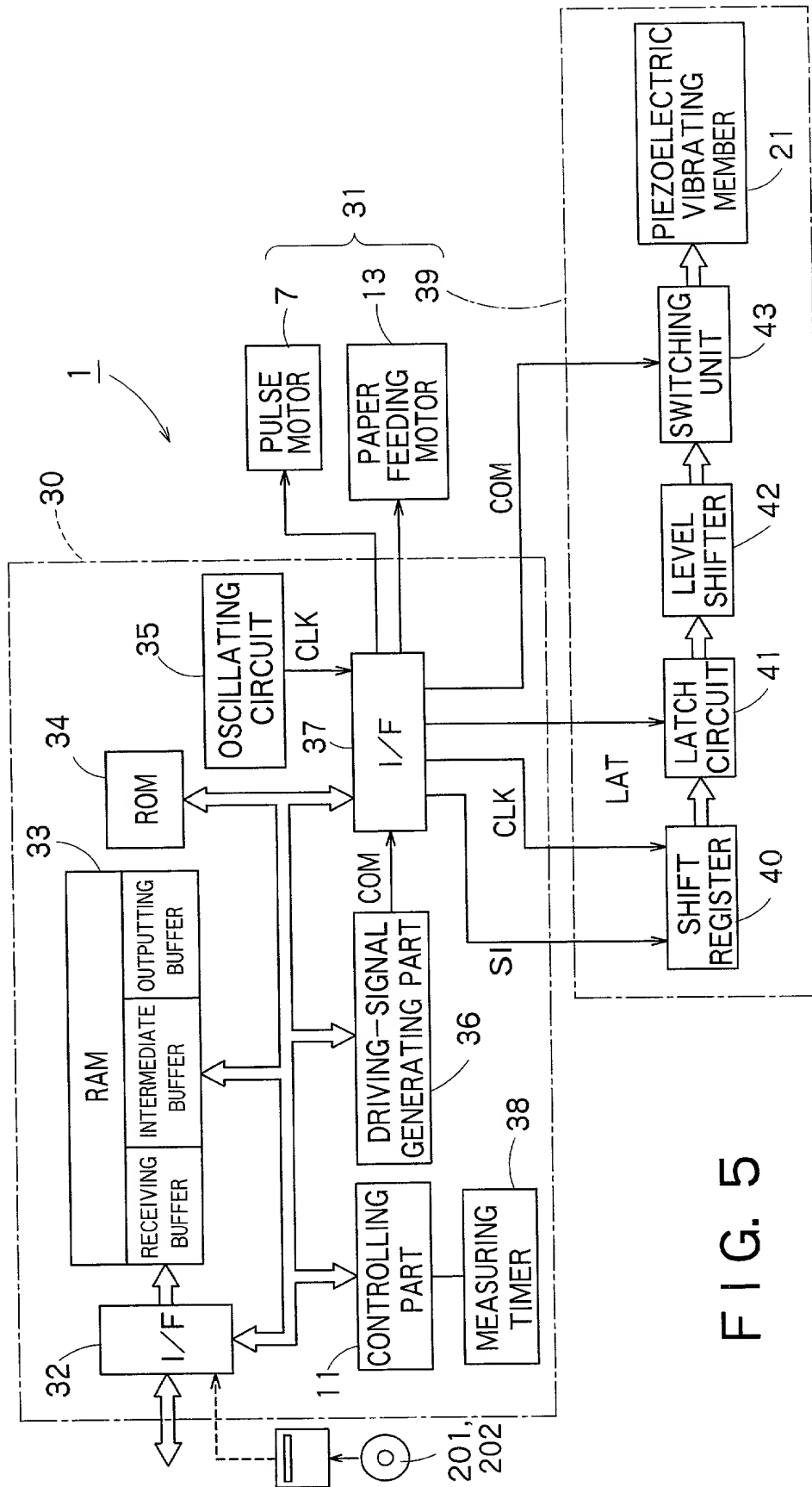
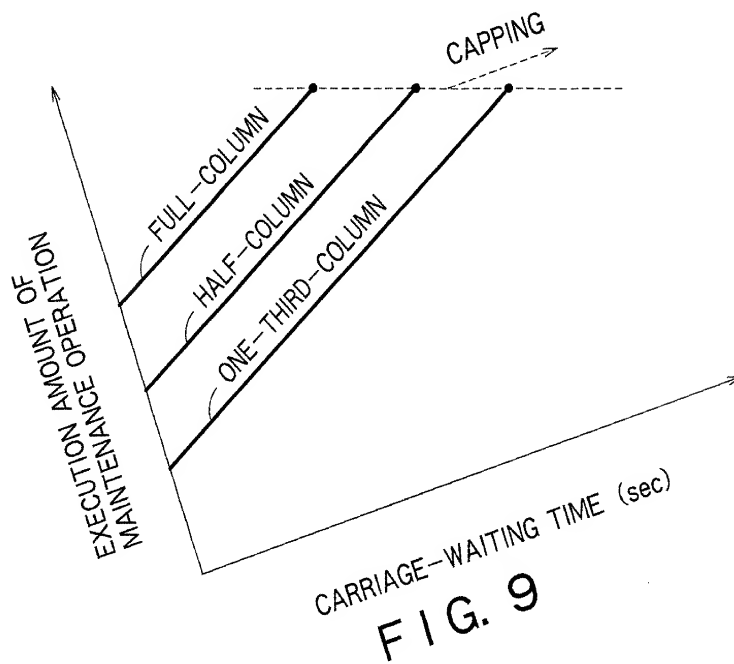
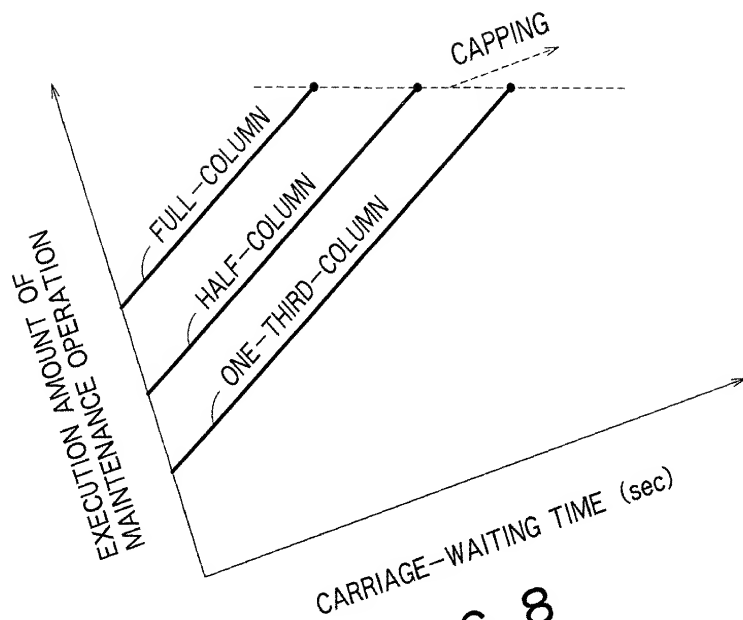


FIG. 4





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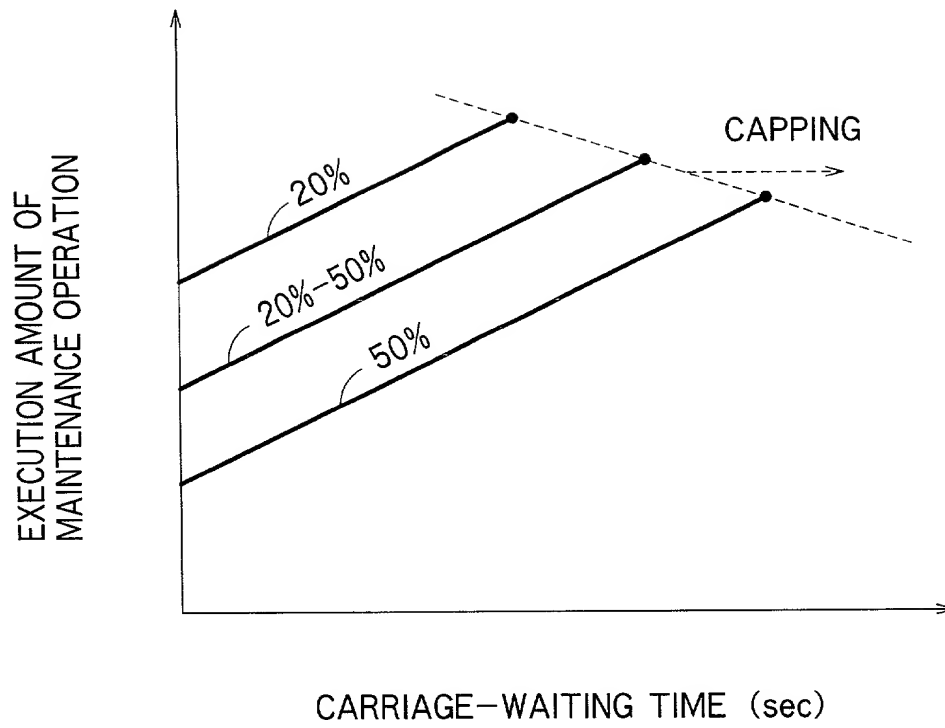


FIG. 10

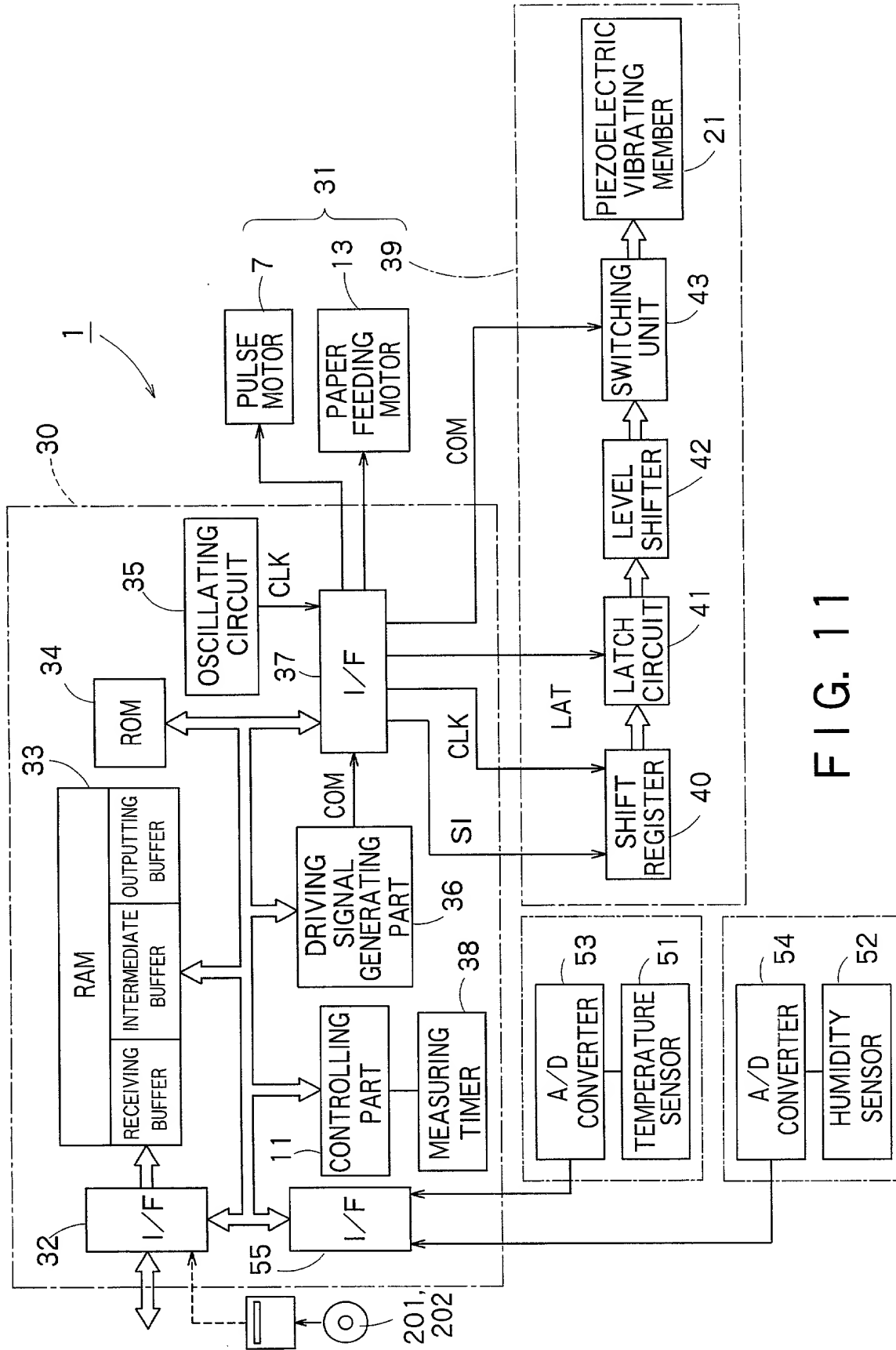


FIG. 11

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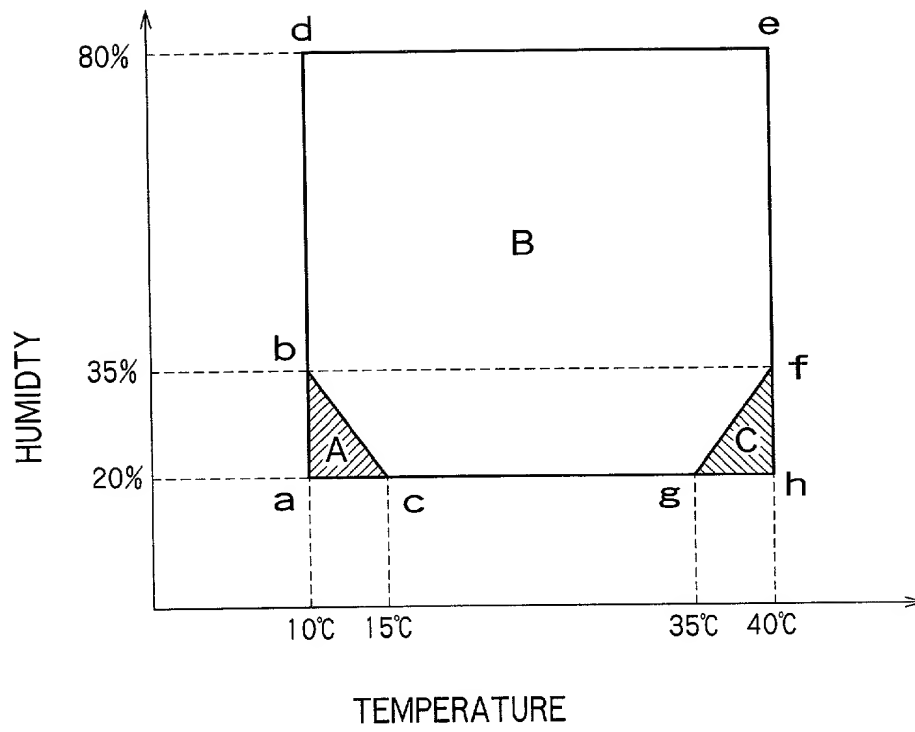


FIG. 12

☒ Original ☐ Supplemental ☐ Substitute ☐ PCT ☐ DESIGN

Title: LIQUID JETTING APPARATUS

() the specification in International Application No. , filed , and as amended on (if applicable).

I acknowledge my duty to disclose to the Patent and Trademark Office all information known to me to be material to patentability as defined in Title 37, Code of Federal Regulations, §1.56.

COUNTRY	APPLICATION NO.	DATE OF FILING	PRIORITY CLAIMED
Japan	1999-291627	October 13, 1999	YES

I hereby claim the benefit under Title 35, United States Code §120 of any United States application(s) listed below and, insofar as the subject matter of each of the claims of this application is not disclosed in the prior United States application in the manner provided by the first paragraph of Title 35, United States Code §112, I acknowledge the duty to disclose information material to patentability as defined in Title 37, Code of Federal Regulations, §1.56 which occurred between the filing date of the prior application and the national or PCT international filing date of this application:

APPLICATION SERIAL NO.	U.S. FILING DATE	STATUS: PATENTED, PENDING, ABANDONED

And I hereby appoint Michael R. Davis, Reg. No. 25,134; Matthew M. Jacob, Reg. No. 25,154; Jeffrey Noltan, Reg. No. 25,408; Warren M. Cheek, Jr., Reg. No. 33,367; Nils Pedersen, Reg. No. 33,145; and Charles R. Watts, Reg. No. 33,142, who together constitute the firm of WENDEROTH, LIND & PONACK, L.L.P., jointly and severally, attorneys to prosecute this application and to transact all business in the U.S. Patent and Trademark Office connected therewith.

I hereby authorize the U.S. attorneys named herein to accept and follow instructions from KYOWA PATENT AND LAW OFFICE as to any action to be taken in the U.S. Patent and Trademark Office regarding this application without direct communication between the U.S. attorneys and myself. In the event of a change in the persons from whom instructions may be taken, the U.S. attorneys named herein will be so notified by me.

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Residence & Citizenship	CITY	STATE OR COUNTRY	COUNTRY OF CITIZENSHIP
Post Office Address	ADDRESS	CITY	STATE OR COUNTRY ZIP CODE
Full Name of Sixth Inventor	FAMILY NAME	FIRST GIVEN NAME	SECOND GIVEN NAME
Residence & Citizenship	CITY	STATE OR COUNTRY	COUNTRY OF CITIZENSHIP
Post Office Address	ADDRESS	CITY	STATE OR COUNTRY ZIP CODE

I further declare that all statements made herein of my own knowledge are true, and that all statements on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under Section 1001 of Title 18 of the United States Code, and that such willful false statements may jeopardize the validity of the application or any patent issuing thereon.

1st Inventor _____ Date _____
Kazunaga SUZUKI
2nd Inventor _____ Date _____
3rd Inventor _____ Date _____
4th Inventor _____ Date _____
5th Inventor _____ Date _____
6th Inventor _____ Date _____

The above application may be more particularly identified as follows:

U.S. Application Serial No. _____ Filing Date October 13, 2000

Applicant Reference Number 127896US Atty Docket No. 2000_1427A

Title of Invention LIQUID JETTING APPARATUS